

器,使系统能够渐进稳定地跟踪期望目标。仿真结果表明,本方案能够减小系统的跟踪误差,并能够使轮齿平稳、连续地传递力矩,有效地消除由齿隙引起的干扰,取得较好的控制效果。

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作者简介:

马艳玲 (1980—),女,硕士研究生,目前研究方向为机电控制,
E-mail: myling289@163.com;

黄进 (1968—),男,博士,教授,目前研究方向为机电控制以及计算机外部设备,E-mail: jhuang@mail.xidian.edu.cn;

张丹 (1982—),女,硕士研究生,目前研究方向为机电控制,
E-mail: caidan930@163.com.

2009年《控制理论与应用》更改刊期

2008年本刊实行远程稿件处理系统以来,稿件处理速度逐渐提高,投稿量明显增加,稿件录用量随之增多。为了缓解稿件积压现象,缩短发表周期,《控制理论与应用》将于2009年起更改刊期,由双月刊改为月刊。欢迎广大专家学者积极投稿。

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